

**In the Claims:**

Please amend the claims as follows:

1. (Currently Amended) Method for performing event detection and object tracking in an image stream, wherein an event is defined as the occurrence of a type of activity in field which requires some type of action in response thereto, said method comprising:
  - a) installing in the field, an image acquisition device for acquiring an image stream and comprising a local programmable processor for converting the acquired image stream, consisting of one or more images, to a digital format, and a local encoder, preprogrammed to operate with an image processing server via a data network on the basis of distribution of image processing algorithms between the local encoder and the server, said local encoder being operable to apply low-level feature extraction to the digital format of ~~for generating, from said image stream, for selectively generating, from said image stream a non-image feature stream data, said non-image feature data including parameters related to attributes of areas in said image stream, and for transmitting the a non-image feature stream via the data network to the image processing server containing said features; and~~
  - b) connecting said image acquisition device to a the data network through a corresponding data communication channel~~[[;]], to enable the operation of the encoder by the image processing server and transmission of the feature steam from the image acquisition device to the image processing server, thereby actuating high-level processing applications at the image processing server to detect the event.~~

- ~~c) — connecting an image processing server to said data network;~~
  - ~~d) — detecting said event from analyzing said non-image feature stream by said image processing server and;~~
  - ~~e) — transmitting, by said image processing server, indications regarding said event in said image streams to an operator.~~
2. (Currently Amended) Method according to claim 1, wherein the local encoder is a composite encoder, ~~being the local encoder that further~~ which comprises circuitry for compressing the image stream, and further comprising:
- a) operating said composite encoder in a first mode, during which it generates and transmits said ~~non-image~~ feature stream to said image processing server, and
  - b) operating said composite encoder in a second mode responsive to detecting said events, during which it transmits to said image processing server, in addition to said ~~non-image~~ feature stream, at least a portion of said image stream in a desired compression level, according to commands sent from said image processing server.
3. (Cancelled)
4. (Original) Method according to claim 1, further comprising decoding one or more compressed image streams containing events by said server, and transmitting the decoded image streams to the display of an operator, for viewing.

5. (Previously Presented) Method according to claim 2, further comprising recording one or more compressed image streams obtained while said local encoder operates in said second mode.
6. (Original) Method according to claim 2, further comprising dynamically allocating additional image processing resources, in the server, to data communication channels that receive image streams.
7. (Cancelled)
8. (Previously Amended) Method according to claim 6, further comprising generating and displaying a graphical polygon that encompasses an object of interest, being within at least one of a frame of an image and an area of interest in said image.
9. (Previously Amended) Method according to claim 8, further comprising generating and displaying a graphical trace indicating the history of movement of an object of interest, being within at least one of the frame of an image and an area of interest in said image.
10. (Previously Amended) Method according to claim 1, wherein the image stream is selected from a group of images that comprises video streams, still images, computer generated images, pre-recorded digital video data and analog video data.
11. (Original) Method according to claim 1, wherein the image streams are video streams, compressed using MPEG format.
12. (Cancelled)

13. (Currently Amended) Method according to claim 1, wherein the ~~non-~~image feature stream data includes at least one of:

- a motion feature;
- foreground feature
- a color feature;
- edge data; and
- frequency related information.

14. (Currently Amended) Method according to claim 1, further comprising performing, by the server, at least one of:

- License Plate Recognition (LPR);
- Facial Recognition (FR);
- detection of traffic rules violations;
- behavior recognition;
- fire detection;
- traffic flow detection; and
- smoke detection,

using the ~~non-image~~ feature stream received from the image acquisition device, through the data communication channel.

15. (Currently Amended) System for use in performing event detection and object tracking in image streams, wherein an event is defined as the occurrence of a type of activity in field which requires some type of action in response thereto, said system comprising:

- a) an image acquisition device, for installation ~~installed in the field, the~~ image acquisition device comprising:

- a. 1) a local programmable processor for converting the acquired image stream to a digital format; and
- a. 2) a local encoder, preprogrammed to operate with an image processing server via a data network on the basis of distribution of image processing algorithms between the image acquisition device and the server, said local encoder being operable for generating, from said image stream, ~~non-image~~ a feature stream data, ~~said non-image feature data~~ including parameters related to attributes of areas in said image stream, ~~and for transmitting a feature stream containing said non-image feature data;~~
- b) ~~a data network, to which the image acquisition device is connected through a corresponding data communication channel~~ connecting the image acquisition device to the data network and operable for transmitting the feature stream generated by the local encoder to the image processing server, thereby actuating high-level processing applications at the image processing server to detect the event in the field;
- c) a remote image processing server connected to said data network, said remote image processing server receiving said feature stream transmitted by said local encoder; and
- d) said remote image processing server detecting said event from analyzing said feature stream, and transmitting indications regarding said event to an operator.

16. (Previously Amended) System according to claim 15, wherein said local encoder is a composite encoder and further comprises circuitry for compressing said image stream, said composite encoder having a first operating mode, during which it generates and transmits said feature stream to said remote image processing server, and having a second operating mode, during which said composite encoder transmits to said remote image processing server, in addition to said feature stream, at least a portion of said image stream in a desired compression level, according to commands sent from said remote image processing server.

17. (Previously Amended) System according to claim 16, further comprising the remote image processing server decoding said portion of said image stream and determining said portion of said image stream contains an event; and

an operator display, for receiving said portion of said image stream, containing the event from the remote image processing server.

18. (Previously Amended) System according to claim 16, further comprising a network video recorder for recording one or more image streams, obtained while said composite encoder operates in said second mode.

19. (Currently Amended) System according to claim ~~16~~ 17, in which the remote image processing server is capable of dynamically allocating image processing resources to said data communication channel when said data communication channel receives said portion of said image stream.

20. (Previously Amended) System according to claim 16, in which said portion of said image stream obtained while operating in the second mode, comprises only a portion of the image that corresponds to a desired area of interest.

21. (Currently Amended) System according to claim 46 17, in which the remote image processing server further comprises processing means for generating and displaying a graphical polygon that encompasses an object of interest, being within at least one of a frame of an image and an area of interest in said image when said composite encoder is in said second operating mode.

22. (Previously Amended) System according to claim 21, in which the remote image processing server further comprises processing means for generating and displaying a graphical trace indicating the history of movement of an object of interest, being within at least one of the frame of said image and the area of interest of said image.

23. (Original) System according to claim 15, in which the image stream is selected from the group of images that comprises video streams, still images, computer generated images, and pre-recorded digital or analog video data.

24. (Previously Amended) System according to claim 15, in which the image stream is a video stream compressed using MPEG format.

25. (Cancelled)

26. (Previously Amended) System according to claim 15, in which the feature stream includes at least one of:

- a motion feature;
- a color feature;
- edge data; and
- frequency related information.

27. (Currently Amended) System according to claim 45 17, in which the remote image processing server further comprises processing means for performing at least one of:

License Plate Recognition (LPR);  
Facial Recognition (FR);  
detection of traffic rules violations;  
behavior recognition;  
fire detection;  
traffic flow detection; and  
smoke detection;

using the feature stream, received from the local encoder of the image acquisition device, through the data communication channel.

28. (Canceled)

29. (Canceled)

30. (Currently Amended) Method according to claim 1 wherein said ~~non-image~~ feature stream ~~data~~ further comprises a motion feature, ~~and~~ said motion feature is being encoded in said feature stream only when said motion feature exceeds a predetermined threshold.

31. (Currently Amended) System according to claim 15 wherein said ~~non-image~~ feature stream ~~data~~ further comprises a motion feature, ~~and~~ said motion feature is being encoded in said feature stream only when said motion feature exceeds a predetermined threshold.

32. (Currently Amended) A distributed image processing method for effectively performing event detection in a large number of concurrent image



sequences, wherein an event is defined as the occurrence of a type of activity in fields which requires some type of action in response thereto, said method comprising:

a) performing low level feature extraction by encoders associated with in the vicinity of an image acquisition devices installed in the fields, said low level feature extraction comprising:

i) receiving ~~an image streams~~ from the each of a plurality of image acquisition devices installed in the fields and generating digital data indicative thereof;

ii) processing the digital data indicative of the image stream and selectively extracting therefrom a corresponding non-image features stream having a bandwidth narrower than that of the corresponding image stream, from features in said feature image stream including from each of said plurality of image acquisition devices, said features being parameters related to attributes of areas in the respective said image stream;

iii) prior to detecting said event, generating a reduced bandwidth non-image feature stream for each said image stream, said reduced bandwidth non-image feature stream based upon said features;

b) ~~prior to detecting said event~~, transmitting said reduced bandwidth ~~non-image feature stream from the for each of said plurality of image acquisition devices to a common remote image processing server, thereby actuating the image processing server for~~ ; and

c) ~~detecting events by performing high level image processing to detect events in the fields, at said remote image processing server, said high level image processing comprising~~;

- i) ~~receiving said reduced bandwidth non-image feature stream transmitted from each of said plurality of image acquisition devices,~~
- ii) ~~analyzing each said reduced bandwidth non-image feature stream at said remote image processing server, and~~
- iii) ~~detecting events in each said image stream based upon said analyzing of each said reduced bandwidth non-image feature stream by said remote image processing server.~~

33. (Currently Amended) The method of claim 32 further comprising transmitting to said remote image processing server at least a portion of an image stream from any of said plurality of image acquisition devices associated with a the reduced bandwidth ~~non-image~~ feature stream in which said remote image processing server detects an event.

34. (Currently Amended) The method of claim 33, wherein said high level image processing comprises: receiving said reduced bandwidth feature stream transmitted from each of said plurality of image acquisition devices, analyzing each said reduced bandwidth feature stream at said remote image processing server, and detecting events in each said image stream based upon said analyzing of each said reduced bandwidth feature stream by said remote image processing server, and further comprising displaying said image stream in which an event is indicated on a display screen of an operator at said remote image processing server.

35. (Currently Amended) The method of claim 32 wherein said selective extraction comprises selectively encoding features ~~are encoded~~ in said reduced bandwidth ~~non-image~~ feature stream only when at least one of a number and type of said features exceed a predetermined threshold, wherein said threshold is applied to said image acquisition device to control when said encoder generates and transmits said feature stream, and said number and type of

features exceeding said threshold are indicative of activity to be further analyzed by said remote image processing server in order to detect said event.

36. (Currently Amended) The method of claim 35 wherein said transmitting said reduced bandwidth ~~non-image~~ feature stream to said remote image processing server occurs only when said number and type of features exceed said predetermined threshold.

37. (Currently Amended) The method of claim 35 wherein said features further comprise motion features, and said motion features are encoded in said reduced bandwidth ~~non-image~~ feature stream only when said motion features exceed said predetermined threshold.

38. (Previously Presented) The method of claim 35 wherein said predetermined threshold is set by said remote server.

39. (Previously Presented) The method of claim 32 further comprises recording said image stream when said event is detected therein.

40. (Currently Amended) The method of claim 35 further comprising transmitting to said remote image processing server at least a portion of an image stream from any of said plurality of image acquisition devices associated with the a reduced bandwidth ~~non-image~~ feature stream in which said remote image processing server detects an event.

41. (Previously Amended) The method of claim 40 further comprising generating and displaying a graphical polygon that encompasses an object of interest within at least one of a frame of said at least a portion of an image and an area of interest in said at least a portion of an image.

42. (Previously Presented) The method of claim 41 further comprising generating and displaying a graphical trace indicating the history of movement of said object of interest.

43. (Previously Amended) The method of claim 32 wherein said image stream is selected from a group of images comprising video streams, still images, computer generated images, pre-recorded digital video data and pre-recorded analog video data.

44. (Currently Amended) The method of claim 32 wherein said ~~non-image~~ features stream comprises at least one of:

- a motion feature;
- a color feature;
- edge data; and
- frequency related information.

45. (Currently Amended) The method of claim ~~32~~ 34 wherein said ~~second processing step further~~ high level image processing comprises performing, by said remote image processing server, at least one of:

- License Plate Recognition (LPR);
- Facial Recognition (FR);
- detection of traffic rules violations;
- behavior recognition;
- fire detection;
- traffic flow detection; and
- smoke detection;

using said reduced bandwidth ~~non-image~~ feature stream received from at least one of said plurality of image acquisition devices.

46. (Currently Amended) A distributed image processing system for effectively performing event detection in a large number of concurrent image sequences, said distributed image processing system having an in field component and a remote component, wherein an event is defined as the occurrence of a type of activity which requires some type of action in response thereto, said distributed image processing system comprising:

a) a low level feature extraction component located in field, said low level feature extraction component comprising:

a plurality of image acquisition devices installed in field, each producing an image stream;

a processor and an encoder associated with each of said plurality of image acquisition devices;

said processor converting said image stream to a digital format;

said encoder selectively extracting ~~non-image~~ feature data from said image stream and generating a reduced bandwidth ~~non-image~~ feature stream therefrom, said ~~non-image~~ feature data including parameters related to attributes of areas in said image stream;

b) a remote high level image processing component comprising a remote image processing server;

c) a data network with which said low level feature extraction component communicates with said remote image processing server, each of said plurality of image acquisition devices and associated encoders communicating with said data network through a corresponding data communication channel;

d) ~~wherein~~ said encoder ~~transmits~~ transmitting said reduced bandwidth ~~non-image~~ feature stream to said remote image processing server ~~prior to~~ for detection of said an event;

e) ~~wherein~~ said remote image processing server ~~analyzes~~ analyzing said reduced bandwidth ~~non-image~~ feature stream and thereby ~~detects~~ detecting said events associated with said image stream ~~from each of said plurality of image acquisition devices~~; and

f) wherein, responsive to detecting said events, said remote image processing server causes at least a portion of said image stream associated with said events to be transmitted to said remote image processing server.

47. (Currently Amended) The system of claim 46 wherein said encoder comprises a composite encoder which incorporates said processor, and further comprises circuitry for compressing said image stream, said composite encoder having a first operating mode during which said composite encoder transmits said reduced bandwidth ~~non-image~~ feature stream to said remote image processing server, and a second operating mode during which said composite encoder transmits to said remote image processing server, in addition to said reduced bandwidth ~~non-image~~ feature stream, at least a portion of said image stream in a desired compression level, according to commands sent from said remote image processing server, said remote image processing server controlling said composite encoder to operate in said second operating mode responsive to detecting said events.

48. (Canceled)

49. (Previously Amended) The system of claim 47 further comprising an operator display for receiving from said remote image processing server said image stream in which said event is detected.

50. (Currently Amended) The system of claim 46 wherein said features are encoded in said reduced bandwidth ~~non-image~~ feature stream only when at least one of a number and type of said features exceed a predetermined threshold, wherein said threshold is applied to said image acquisition device to control when said encoder generates and transmits said feature stream, and said number and type of features exceeding said threshold are indicative of activity to be further analyzed by said remote image processing server in order to detect said event.

51 (Currently Amended) The method of claim 50 wherein said reduced bandwidth ~~non-image~~ feature stream is transmitted to said remote image processing server only when said number and type of features exceed said predetermined threshold.

52. (Currently Amended) The system of claim 50 wherein said features further comprise motion features, and said motion features are encoded in said reduced bandwidth ~~non-image~~ feature stream only when said motion features exceed said predetermined threshold.

53. (Previously Presented) The system of claim 50 wherein said predetermined threshold is established by said remote image processing server.

54. (Previously Amended) The system of claim 47 further comprising a network video recorder associated with each of said plurality of image acquisition devices for recording said image stream when said composite encoder operates in said second operating mode.

55. (Previously Presented) The system of claim 47 wherein said remote image processing server dynamically allocates additional image processing resources to data communication channels receiving said image stream.

56. (Cancelled)

57. (Previously Amended) The system of claim 49 wherein said remote image processing server further comprises a programmable processor for generating and displaying on said operator display a graphical polygon that encompasses an object of interest within at least one of a frame of said at least a portion of an image and an area of interest in said at least a portion of an image.

58. (Previously Presented) The system of claim 57 wherein said remote image processing server generates and displays on said operator display a graphical trace indicating a history of movement of said object of interest.

59. (Previously Amended) The system of claim 46 wherein said image stream is selected from a group of images comprising video streams, still images, computer generated images, pre-recorded digital video data and pre-recorded analog video data.

60. (Currently Amended) The system of claim 46 wherein said ~~non-~~image features stream comprises at least one of:

- a motion feature;
- a color feature;
- edge data; and
- frequency related information.



61. (Currently Amended) The system of claim 46 wherein said remote image processing server performs at least one of:

- License Plate Recognition (LPR);
- Facial Recognition (FR);
- detection of traffic rules violations;
- behavior recognition;
- fire detection;
- traffic flow detection; and
- smoke detection;
- using said reduced bandwidth non-image feature stream.

Please add claims 62-66 as follows:

62. (New) Method for use in performing event detection and object tracking in image streams using a system formed by a set of image acquisition devices, each installed in field where an event is to be detected and connected to a central station through a data network, the method comprising:

- processing a digital format of an image stream, consisting of one or more images, to detect features, being parameters related to attributes of objects in said image stream, and, based on these features, performing the event detection and object tracking, wherein

- providing an image processing server remote from the field, said image processing server being preprogrammed to operate with each of the image acquisition devices on the basis of distribution of image processing algorithms between the image acquisition device and the server, said image processing server being preprogrammed for performing said distribution of image processing algorithms by carrying out the following:

- dynamically determining a threshold value for each feature, which is associated with the event to be detected and which is to be extracted by

the set of image acquisition devices from image data acquired thereby in the field, and updating each of the image acquisition devices with the corresponding threshold,

in response to a feature stream, received from each of the image acquisition devices via the network, applying a high-level processing to the received feature stream to identify events in an image data to which said feature stream corresponds, and controlling an operational mode of the respective image acquisition device, to thereby enable ~~transmit~~ transmission of output data to an operator.

63. (New) A computer readable medium for use in performing event detection and extraction and object tracking, the computer readable medium containing instructions which, when executed by a processor, cause the processor to operate with each of multiple remote image acquisition devices via a communication network on the basis of distribution of image processing algorithms between the image acquisition device and said processor, by selectively carrying out the following:

dynamically determining a threshold value for each of a plurality of predetermined features, which are parameters related to attributes of objects in an image stream to be captured by at least one of the remote image acquisition devices, and are associated with the event to be detected and extracted by the respective image acquisition device from image data acquired thereby in the field, and updating each of the image acquisition devices with the corresponding threshold,

in response to a feature stream, received from at least one of the image acquisition devices via the network, processing the feature stream by applying a high-level processing to the received feature stream to identify events in an image data to which said feature stream corresponds, and controlling an operational mode of the respective image acquisition device, to thereby enable transmission of output data to an operator.

64. (New) System for use in performing event detection and object tracking in image streams, the system comprising an image processing server configured for connecting via a data network to a set of image acquisition devices each located in field where the event detection is to be performed, said image processing server being preprogrammed to operate with each of the image acquisition devices on the basis of distribution of image processing algorithms between the image acquisition devices and the image processing server, by determining and providing to each of the image acquisition devices a corresponding threshold for each feature that is associated with the event to be detected and is to be extracted by the image acquisition devices from image data acquired thereby, the image processing server being responsive to a feature stream, received from each of the image acquisition devices for applying high-level processing to the received feature stream, to control an operational mode of the respective image acquisition device and to identify events in the image data corresponding to the feature stream, to thereby enable transmission of output data to an operator.

65. (New) A computer program for use in performing event detection and object tracking in image streams, comprising computer program code means which, when run on a computer causes the computer to:

connect, via a data network, an image processing server to a set of image acquisition devices, each located in field where the event detection is to be performed; and

cause the image processing server to operate with each of the image acquisition devices on the basis of distribution of image processing algorithms between the image acquisition devices and the image processing server by determining and providing to each of the image acquisition devices a corresponding threshold for each feature that is associated with the event to be detected and is to be extracted by the image acquisition devices from image data

acquired thereby, the image processing server being responsive to a feature stream, received from each of the image acquisition devices for applying high-level processing to the received feature stream, to control an operational mode of the respective image acquisition device and to identify events in the image data corresponding to the feature stream, to thereby enable transmission of output data to an operator.

66. (New) The computer program as claimed in Claim 65 embedded on a computer readable medium.